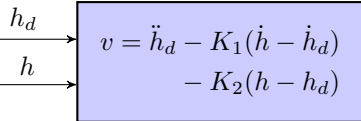
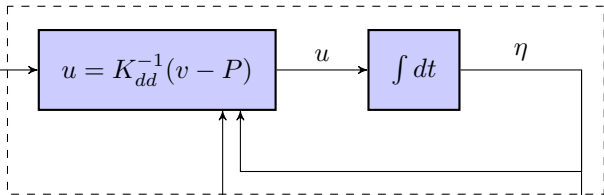


Input-output linear submodel

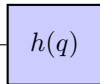
Feedback control



Dynamic linearisation



Output function



Object

